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FTT-SE: Towards flexible/open Cyber-Physical Systems

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Unifying frameworks Networked Monitoring Internet and Control of Things Vehicular **Networks Cyber-Physical Systems** Focus on • Real-time Anything that involves computer-environment Modeling (Distributed) **Netwo** Adaptation Embedded Embed **Systems** Control System

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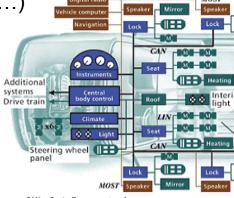
Cyber-Physical Systems

Complex structure

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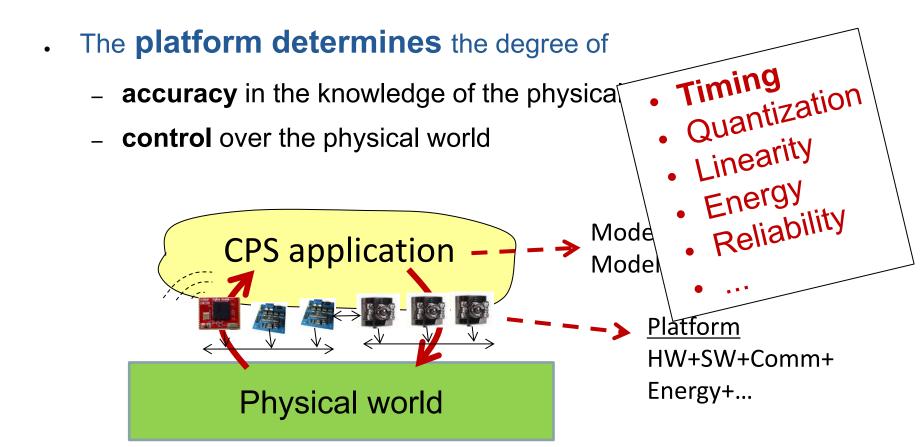
- High heterogeneity (functionality, requirements, resources...)
- Variable composition (versions, modes, connections...)
- Need to be robust with respect to
 - Topology changes (reconfigurations, node crashes, ...)
 - Changes in available resources (energy, bandwidth...)
 - Denial-of-service (malfunctioning nodes, malicious actions...)
 - Intrusion (unauthorized accesses or actions...)

How to design these systems ??



- CAN Controller area network GPS Global Positioning System
- GSM Global System for Mobile Communications
- LIN Local interconnect network MOST Media-oriented systems transport

Cyber-Physical Systems: *internals*

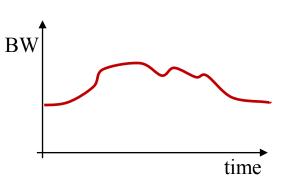




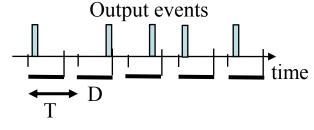
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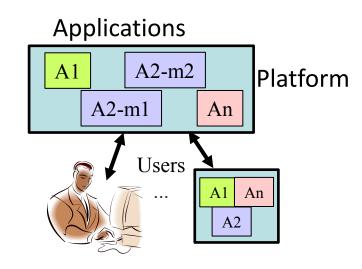
Real-time capable platforms

- . Amenable to modeling of timing behavior
 - Bounded and computable delays
 - \rightarrow real-time guarantees
- While supporting multiple and varying
 - applications, users, operating conditions, ...
- And being resource efficient
 - bandwidth, energy



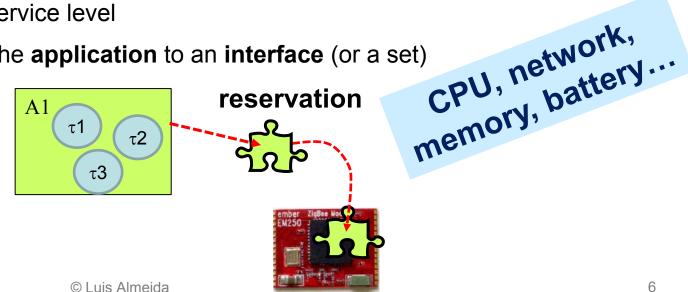






Resource reservation paradigm

- Define the application non-functional requirements ٠
 - Performance & time behavior \rightarrow BW, rate, latency, jitter
 - Possibly with multiple levels of service
- Define how much of each resource is needed
 - To cover the requirements (demand)
 - For each service level
 - Reducing the **application** to an **interface** (or a set)



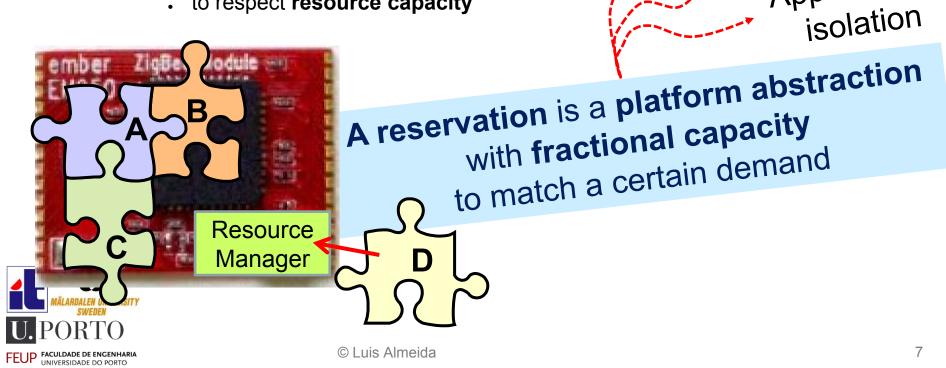


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Resource reservation paradigm

Resource Manager needed

- **Provide reservations** (partitions...)
 - . that match demand
- **Keep track** of accepted reservations
 - to respect resource capacity



Virtualization

Consolidation

Applications

Networks for CPS

Are current networks adequate?

- **Real-Time communication** technologies
 - well developed for (static) DES
 - . focused on latency and isolation

- General purpose communication technlologies

- well developed for large networks (Cloud / Internet)
- essentially best-effort (particularly in access networks)
- focused on openness, scalability and throughput

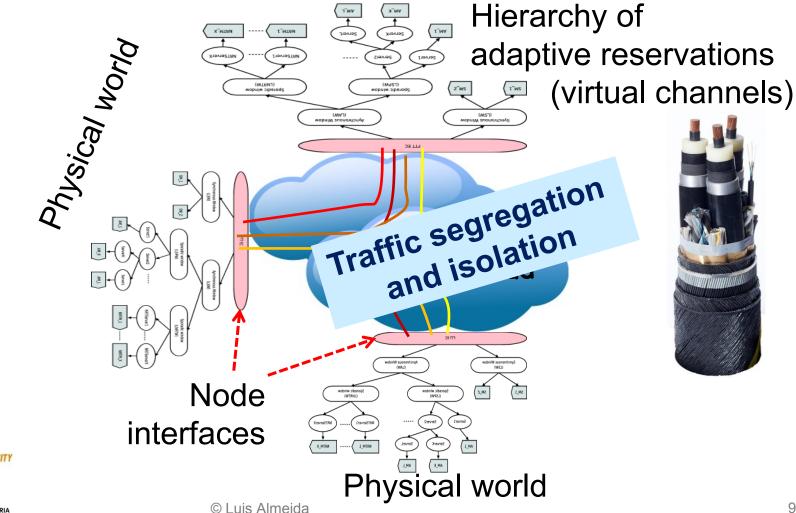
Unifying effort needed, towards scalable, open and efficient real-time communication

CAN EtherCAT TTEthernet ... PROFINET-IRT

> MPLS SDN TCP/UDP RSVP-TE LTE SG ***

A Network Challenge for CPS

The real-time enabled cloud





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Our approaches

Centralized resource manager

- The Flexible Time-Triggered paradigm
 - . Isochronous / asynchronous traffic
 - . Any on-line traffic scheduling supported
- Building on top of Linux-TC
 - Asynchronous traffic, only
- Distributed resource manager
 - The Reconfigurable and Adaptive TDMA protocol
 - · Used in wireless networks on top of CSMA-CA
 - . Isochronous / asynchronous traffic

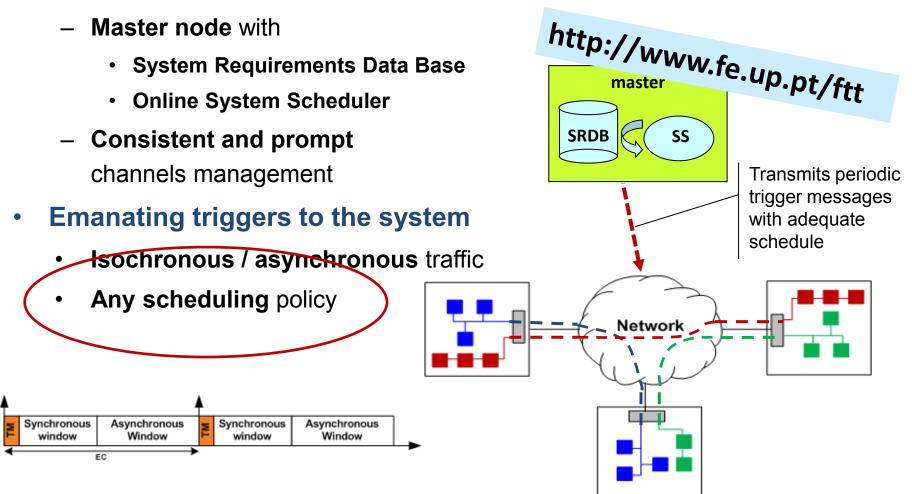




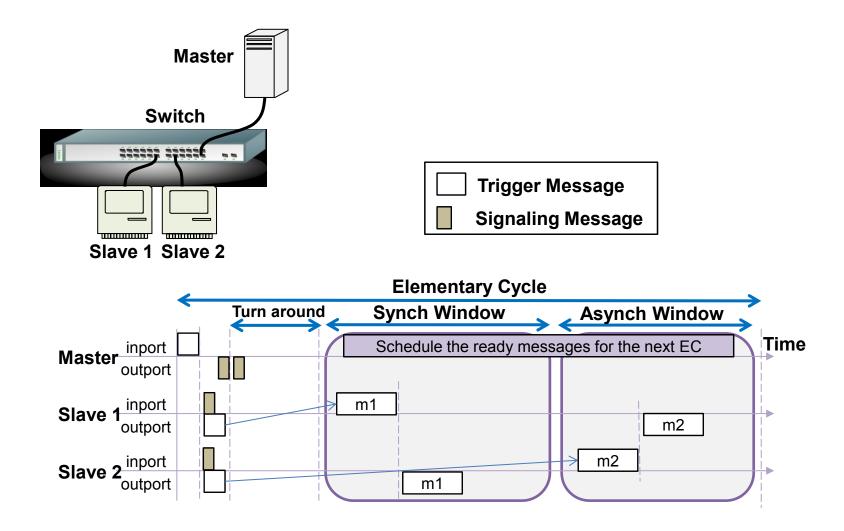
Flexible Time-Triggered architecture

The Flexible Time-Triggered paradigm

Concentration of operational information

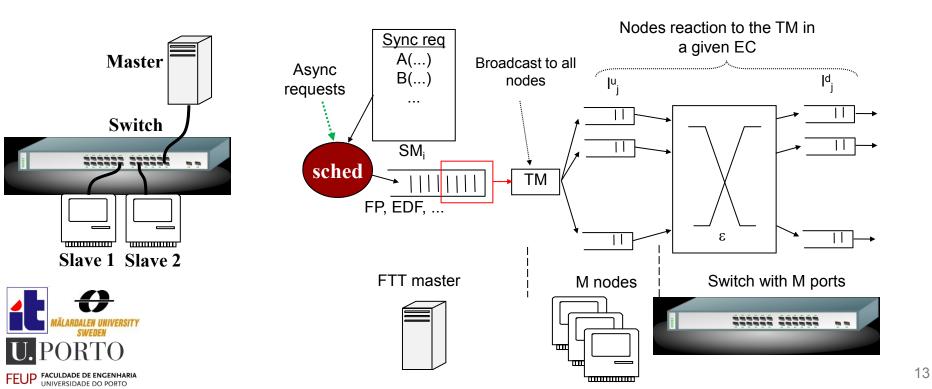


FTT-SE: FTT applied to Switched Ethernet



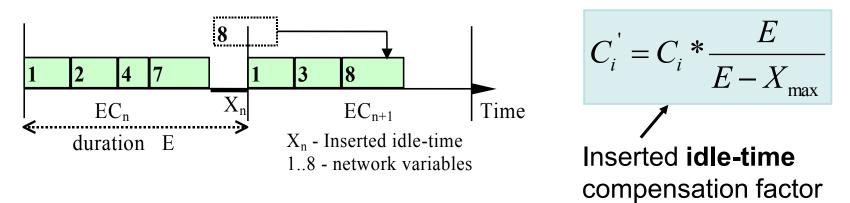
Integrated scheduler for all traffic types

Sync:SRT = { SM_i : $SM_i(C_i, D_i, T_i, O_i, Pr_i, S_i, {R^1_i ... R^{k_i}})$, i=1...N_S}Async:ART = { AM_i : $AM_i(C_i, D_i, mit_i, Pr_i, S_i, {R^1_i ... R^{k_i}})$, i=1...N_A}



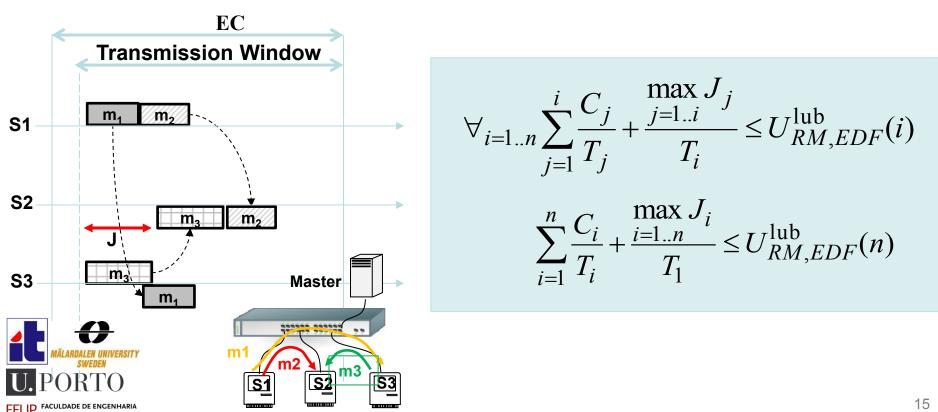
Basic scheduling model:

- Schedule within partitions with strict time bounds
- Use inserted idle-time (X)
 - . There is no blocking
 - Any analysis for preemptive scheduling can be used with inflated transmission times (C')





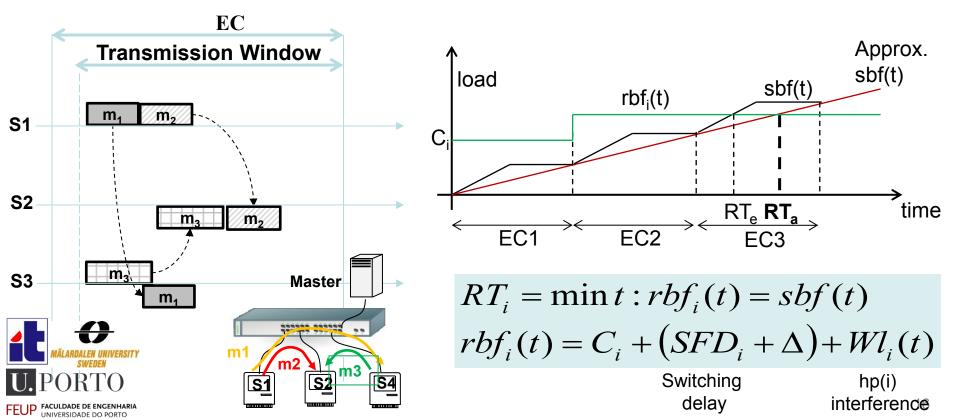
- Utilization bounds for on-line BW management
 - To be applied to each link separately
 - Interference in the uplinks appears at the downlinks as release jitter (J)



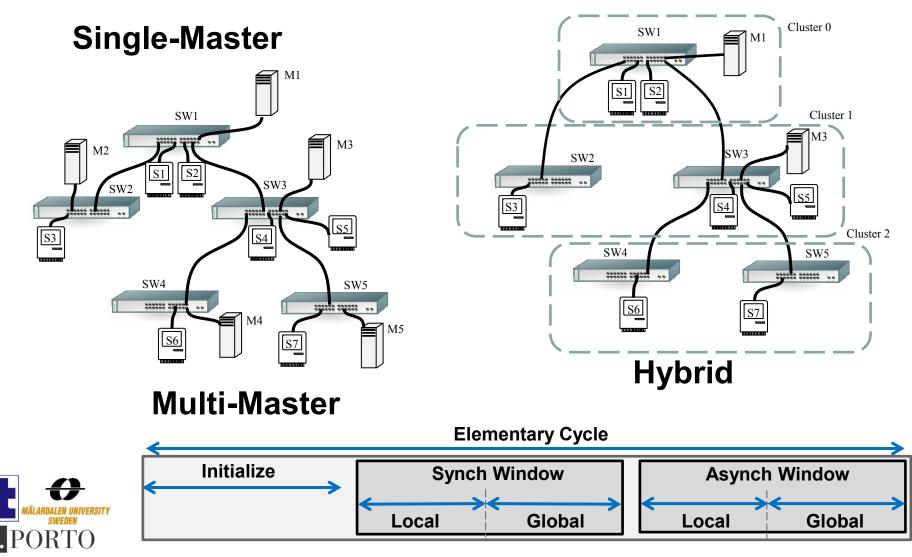
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Response-time analysis

- request bound funtion (rbf): Max. submitted load & interference
- supply bound function (sbf): Min. effective network capacity



Multi-switch FTT-SE architectures



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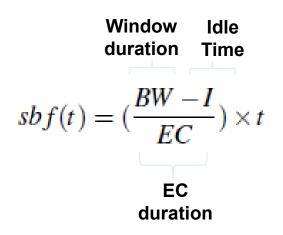
Multi-hop Delay Analysis

request bound function

$$rbf_{i}(t) = C_{i} + sn_{i} \times (SFD_{i} + \Delta) + Wl_{i}(t) + Wr_{i}(t)$$

Switching delay Shared Remote
Link Link Delay Delay

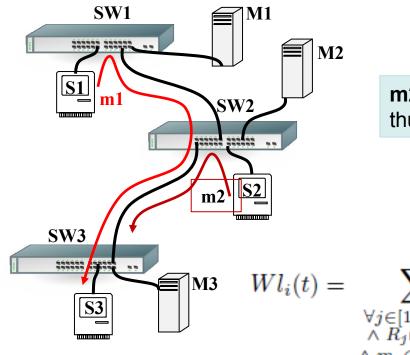
supply bound function





Traffic Delay Analysis

Shared Link Delay



m2 has higher priority than m1, thus causing delay

$$Wl_{i}(t) = \sum_{\substack{\forall j \in [1,n], j \neq i \\ \land R_{j} \cap R_{i} \neq 0 \\ \land m_{j} \in hp(m_{i}) \\ \land m_{j} \in WT(m_{i})}} \lceil \frac{t}{T_{j}} \rceil (C_{j} + sn_{j} \times (SFD_{j} + \Delta))$$



Improved Response-Time Analysis

Revisiting the Shared Link Delay

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$$Wl_{i}(t) = \sum_{\substack{\forall j \in [1,n], j \neq i \\ \land R_{j} \cap R_{i} \neq 0 \\ \land m_{j} \in WT(m_{i})}} \left[C_{j} + sn_{j} \times (SFD_{j} + \Delta) \right]$$

$$Wl_{i}(t) = \sum_{\substack{\forall j \in [1,n], j \neq i \\ \land m_{j} \in WT(m_{i}) \\ \land m_{j} \in WT(m_{i})}} \left[\frac{t}{T_{j}} \right] (C_{j}) + Is_{i}(t) \right]$$

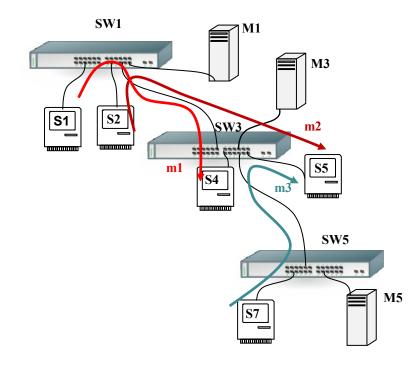
$$G \text{ contains an upper bound on the number of switching delays from each message that contribute to the Shared Link Delay at time t}$$

$$Hs_{i}(t) = \sum_{l=1}^{z(t)} G_{i}^{sort}(t)[l] \quad z(t) = \left\lceil \frac{t}{EC} \right\rceil$$

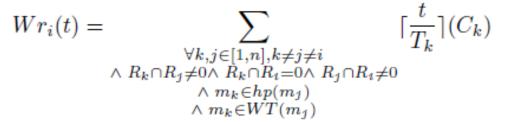
$$We \text{ select the first } z(t) \text{ elements (which are the largest) for each } t$$

Traffic Delay Analysis

Remote Link Delay



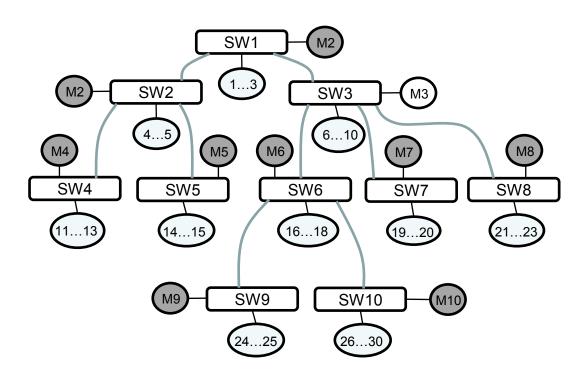
Scheduling of **m1 can push m3 via m2**, despite m1 and m3 not sharing links.





Assessing the Analysis

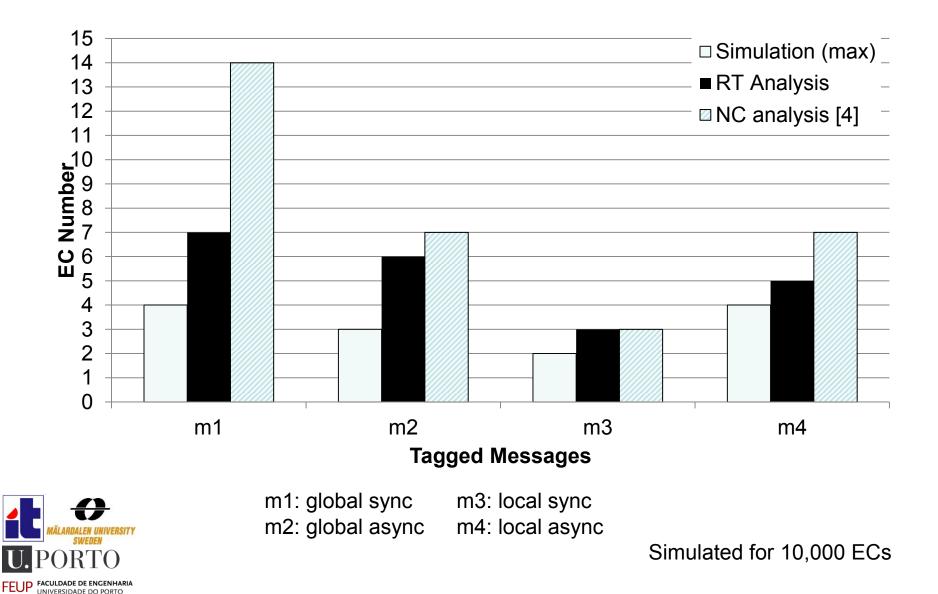
- 10 switches
- 30 nodes
- EC = 10ms
- C = 100Mbps
- Sync local win = 1.5ms
- Sync global win = 2ms
- Async local win = 1.5ms
- Async global win = 4.4ms
- 4 clusters each 1.1ms



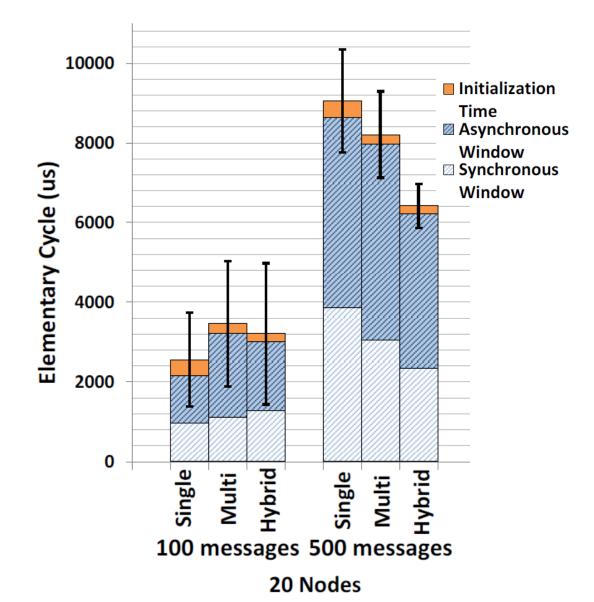
- 90 messages with random parameters
- Worst-case scenario for 4 messages (one per each type)
 - Long route, different activation of interfering messages, priorities



Assessing the Analysis



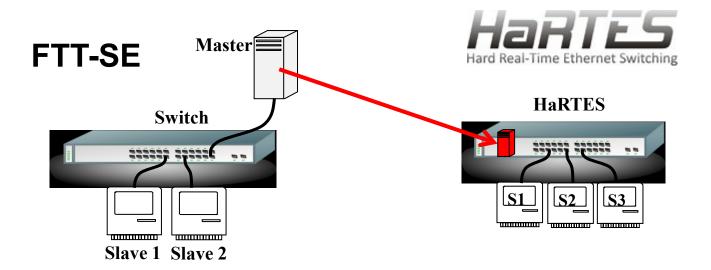
Comparing the multi-hop approaches





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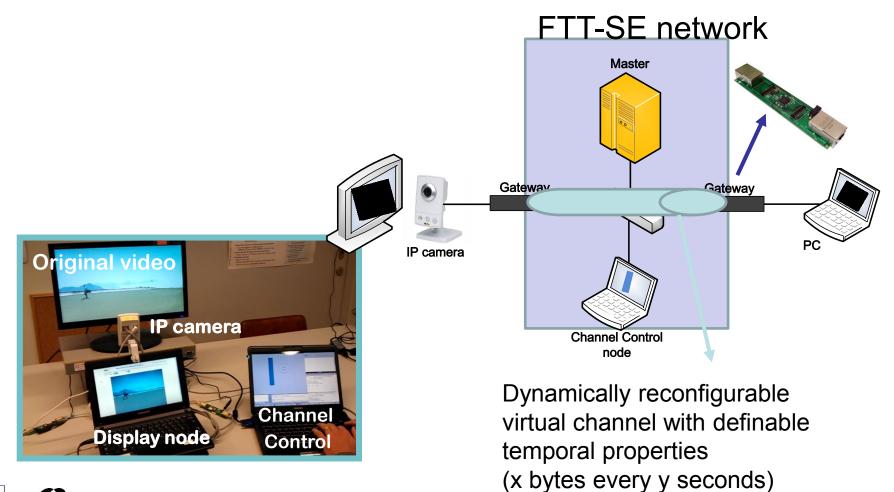
From FTT-SE to HaRTES



- Master integrated in the switch
- Asynchronous & NRT traffic **shaped** by the switch
- Allows direct connection of non-FTT nodes



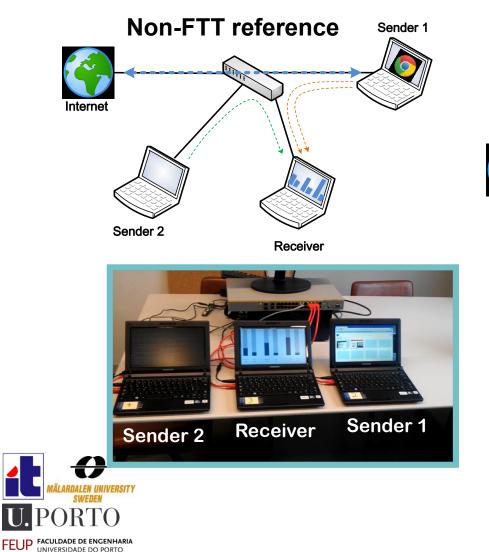
Channel control in FTT-SE

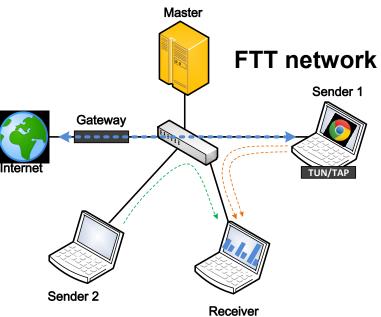


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Temporal isolation in FTT-SE

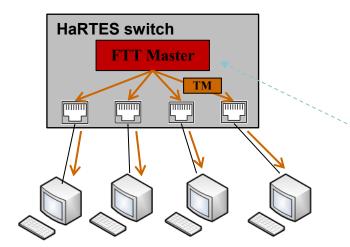




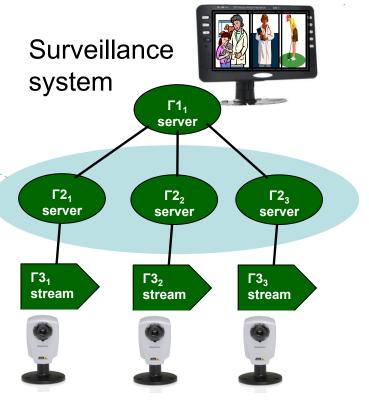
Max interference on FTT-SE channels:

- With graphical interface, < $500\mu s$
- Without graphical interface, < 50µs

Dynamic QoS management with HaRTES



 Only 1 server is allowed with more BW at a time.
 Constant total BW





IP cameras programmed with constant frame rate

Insufficient total bandwidth \rightarrow frame drops w/ TCP/IP sync

Wrapping up

Communications in CPS

- Resource reservations provide composable virtual channels
 - Supporting traffic segregation and isolation
- Efficiency requires reconfigurable and adaptive reservations
 - Adapting channels to actual use and resource availability
- The Flexible Time-Triggered paradigm
 - Provides a centralized network resource manager
 - . Enforces reservations with the desired operational flexibility
 - Can scale to multi-master topologies using a clustered approach



Some pending issues

- How strong/robust and how relevant is enforcing proper resource usage (the partitioning) ?
- Control over resources and flexibility management imply extra
 resource needs (BW, CPU, energy ...) !
 - Also imply extra complexity! With potential for lower reliability!
- How to divide free resource capacity among current reservations?
 - Equally, elastic models (weighted), greedy models, ...
 - How much does the application benefit?
- . Global resource reservations management protocols ...
- New technologies...



Software Defined Networks (wired), LTE, 5G (wireless)...

Questions?

A few acknowledgements:

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